# Search Engines WS 2009 / 2010

Lecture 5, Thursday November 19<sup>th</sup>, 2009 (Efficient List Intersection)

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### Overview of today's Lecture

#### List intersection

 you already know that it is at the core of what every search engine does (no fast search without fast list intersection)

- revisit standard (linear-time) algorithm
- prove a lower bound (how fast can we get)
- algorithm that achieves a matching upper bound
- But before that
  - do missing proof for Golomb encoding from the last lecture
  - talk a bit about the exercises (again)

### Golomb encoding (again)

- By Solomon Golomb, 1966
  - comes with a parameter M (modulus)
  - write positive integer x as  $q \cdot M + r$
  - where  $q = x \operatorname{div} M$  and  $r = x \operatorname{mod} M$
  - the codeword for x is then the concatenation of
    - the quotient q written in unary with 0s
    - a single 1 (as a delimiter)
    - the remainder **r** written in binary
  - examples



Solomon Golomb \*1932 Maryland

Golomb Encoding — Analysis

Show that Golomb encoding is optimal

- for gap-encoding inverted lists
- assuming the doc ids in a list of size m are a random subset of size m of all doc ids 1...n

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[the proof]

### On the exercises

#### Amount

- Should be less work this time
- Do you prefer theoretical or practical or a mix?
- About the aspect of well-specifiedness
  - I am aware that the exercises are often not fully specified

- this requires two things from your side
  - apply your common sense
  - in the case of doubt ask (intelligently)
- these are two super-important skills to learn
  - real-life (research) problems are always ill-specifed
    - (and actually much worse than in the exercises!)
  - common sense + communication are a must

### List Intersection — Standard Algorithm

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For two lists A, B of sizes n and m:

[pseudocode of standard algorithm]

- Two "engineering" problems with the previous code
  - there is an if-statement for each iteration of the loop why is that a problem?
    - modern processors do pipelining = execute future instruction while current instruction is not yet finished

- in the case of an if, the processor tries to predict which part gets executed (so-called branch prediction)
- if the prediction fails, the speculative execution of the future instructions has to be rolled back
- 2. the if-condition is also quite complex
  - costly to evaluate that in each iteration

### List Intersection — Improved Version

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This code is (or can be) significantly faster:

[pseudocode of improved algorithm]

- Can we do better than order n + m ?
  - if we want to compute the \*union\* of the two lists, we obviously can not

- we have to output n + m elements in any case
- for intersection we obviously can for special cases
  - for example: largest element of one list is smaller than smallest element of other list
  - then we can tell after one comparison that the intersection is empty
- how about the general case
- Problem from now on
  - "locate" element from one list in the other list

Let's first try to improve on the standard algorithm

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- what if one list is much smaller than the other list?
  - length of smaller list is k
  - length of larger list is m
- then we can binary search each element of the smaller list in the larger list

[an illustration of this]

- complexity is  $\sim k \cdot \log_2 m$
- this is obviously better than k + m when  $k \ll m$

#### Simple observation:

- if the previous element has been located at position i, the next binary search need only look at positions  $\geq$  i

[an illustration of this]

- Does this help us?
  - in the best case: [short calculation]
  - in the worst case: [short calculation]
  - in the "average" case: [short calculation]

Recall the lower bound for sorting n integers

- there are **n!** possible outputs
- the algorithm has to distinguish between all of them

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- each comparison distinguishes between two cases
- hence we need at least log<sub>2</sub> n! comparisons
- by Stirling's formula  $(n/e)^n \le n! \le n^n$
- hence  $\log_2 n! \sim n \cdot \log n$
- hence every comparison-based sorting algorithm has a running time of  $\Omega(n \cdot \log n)$
- Note: not true for non-comparison based algorithms:

[explain by example 0-1 sequence]

Let's try the same for merging two lists A and B

- that is, locate each element from A in B
- again let k and m = number of elements in A and B resp.

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- same argument: how many ways are there to locate the k elements from A in the m elements from B
- observe: each such way corresponds to a tuple  $(i_1, ..., i_k)$ where  $0 \le i_1 \le ... \le i_k \le m$

(  $i_j$  is simply the location of the j-th element of A in B , location 0 means before the first element, location i > 0 means after the i-th element )

– how many such tuples are there?

There is a similar quantity which is easy to count

- the number of tuples  $(i_1, ..., i_k)$  where  $1 \le i_1 < ... < i_k \le n$ 

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- this is just the number of size-k subsets of  $\{1, ..., n\}$
- and the number of those is n over  $k = n! / (k! \cdot (n-k)!)$
- which by Stirling's formula is approximately (e-n/k)<sup>k</sup>

[relate the two kinds of quantities + prove the lower bound]



## List Intersection — Matching Upper Bound

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#### Idea:

- after previous element from A has been located in B
- start search from that location
- but try to search not much further than next location

[an illustration of this]

- trick: first \*exponentional\* search, then binary search
- if the difference from the previous to the next location is
  d, this can be done in time O(d)

#### Terminology

– Let  $d_1$ , ...,  $d_k$  be the gaps between the locations of the k elements of A in B

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- $(d_1 = from beginning to first location)$
- note that  $\Sigma_i d_i \leq m =$  number of elements in B
- then the time complexity of the algorithm is  $O(\Sigma_i \log d_i)$

[derive upper bound in terms of k and m]